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IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Applicant: Hiroaki Matsumoto

Conf. No.: 1887

Serial No.:10/756,392

Group Art Unit: No. 3683

Filed: January 14, 2004

Examiner: Thomas Williams

For: BRAKE CONTROL APPARATUS

**SUPPLEMENTAL TO THE SUPPLEMENTAL INFORMATION DISCLOSURE
STATEMENT FILED ON MARCH 31, 2006**

Commissioner of Patents
U.S. Patent and Trademark Office
Customer Window, Mail Stop Amendment
Randolph Building
401 Dulany Street
Alexandria, VA 22314
Sir:

Consistent with the Supplemental Information Disclosure Statement filed on March 31, 2006, the following are English language translations of the documents listed in the Supplemental Information Disclosure Statement filed on March 31, 2006:

(1) English language translation of publication entitled Study on Vehicle ABS (3 sheets) which published on June 30, 1993. A copy of this publication is also enclosed with certain headings being translated into English; and

(2) English language translation of publication entitled Performance of Vehicular Movement and Mechanism of Chassis (3 sheets) which published on September 10, 1994. A copy of this publication is also enclosed with certain headings being translated into English.

P27376.A12

Copies of documents (1) and (2) are enclosed. A completed copy of the PTO-1449 Form listing all of the above-listed documents is also enclosed. Accordingly, the Examiner is requested to consider documents (1) and (2) and to indicate such consideration by returning a signed initialed copy of the PTO-1449 form with the next official communication.

Applicant submits that no additional fee is required as Applicant has submitted the required fee when Applicant filed the Supplemental Information Disclosure Statement filed on March 31, 2006.

The Commissioner is hereby authorized to charge any additional fees concerning the application to Deposit Account No. 19-0089.

Respectfully submitted,
Hiroaki Matsumoto

A handwritten signature in black ink, appearing to read 'Andrew M. Calderon', with a long horizontal flourish extending to the right.

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April 13, 2006
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INFORMATION DISCLOSURE STATEMENT BY APPLICANT (Not for submission under 37 CFR 1.99)	Application Number		10756392
	Filing Date		2004-01-14
	First Named Inventor	Hiroaki MATSUMOTO	
	Art Unit	3683	
	Examiner Name	Thomas Williams	
	Attorney Docket Number	P27376	

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**INFORMATION DISCLOSURE
STATEMENT BY APPLICANT**
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Application Number 10756392

Filing Date 2004-01-14

First Named Inventor Hiroaki MATSUMOTO

Art Unit 3683

Examiner Name Thomas Williams

Attorney Docket Number P27376

1

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☐

2

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⁴ Kind of document by the appropriate symbols as indicated on the document under WIPO Standard ST.16 if possible. ⁵ Applicant is to place a check mark here if English language translation is attached.

**INFORMATION DISCLOSURE
STATEMENT BY APPLICANT**
(Not for submission under 37 CFR 1.99)

Application Number	10756392
Filing Date	2004-01-14
First Named Inventor	Hiroaki MATSUMOTO
Art Unit	3683
Examiner Name	Thomas Williams
Attorney Docket Number	P27376

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Please see 37 CFR 1.97 and 1.98 to make the appropriate selection(s):

☐ That each item of information contained in the information disclosure statement was first cited in any communication from a foreign patent office in a counterpart foreign application not more than three months prior to the filing of the information disclosure statement.

OR

☐ That no item of information contained in the information disclosure statement was cited in a communication from a foreign patent office in a counterpart foreign application, and, to the knowledge of the person signing the certification after making reasonable inquiry, no item of information contained in the information disclosure statement was known to any individual designated in 37 CFR 1.56(c) more than three months prior to the filing of the information disclosure statement.

☐ See attached certification statement.

☐ Fee set forth in 37 CFR 1.17 (p) has been submitted herewith.

☐ None

SIGNATURE

A signature of the applicant or representative is required in accordance with CFR 1.33, 10.18. Please see CFR 1.4(d) for the form of the signature.

Signature		Date (YYYY-MM-DD)	
Name/Print	/Andrew M. Calderon/	Registration Number	38,093

This collection of information is required by 37 CFR 1.97 and 1.98. The information is required to obtain or retain a benefit by the public which is to file (and by the USPTO to process) an application. Confidentiality is governed by 35 U.S.C. 122 and 37 CFR 1.14. This collection is estimated to take 1 hour to complete, including gathering, preparing and submitting the completed application form to the USPTO. Time will vary depending upon the individual case. Any comments on the amount of time you require to complete this form and/or suggestions for reducing this burden, should be sent to the Chief Information Officer, U.S. Patent and Trademark Office, U.S. Department of Commerce, P.O. Box 1450, Alexandria, VA 22313-1450. DO NOT SEND FEES OR COMPLETED FORMS TO THIS ADDRESS. SEND TO: Commissioner for Patents, P.O. Box 1450, Alexandria, VA 22313-1450.

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("Study on Vehicle ABS")

.....As Fig. 2-6 shows, the vehicle undergoes a movement which is a combination of the above described two phenomena. In other words, regardless of driver's steering, the vehicle slides along a tangential direction of the curb while spinning irregularly.

As described above, although it is possible to effectively stop a vehicle by braking with a suitable strength, over-braking can lock up the wheels, which is the largest cause for various dangerous vehicle movements. Therefore, a driver must always be careful to avoid locking up the wheels by braking according to road and driving conditions, such as a freezing road, a snowy road, a graveled road, a rough road, a wet road, a dry road, a straight road, a curb, the speed of the vehicle, steering, and the like.

2.1.2. Shifting of load

The weight of a vehicle is supported by the wheels. Therefore, as shown in Fig. 2-7, a vertical force, called a tire load, acts on the contact area of a tire and the road surface. Because of a braking force due to braking and an inertia force (mass \times acceleration/deacceleration), which acts on the center of gravity of the vehicle due to a centrifugal force when cornering, the tire load changes as follows.

(1) Change due to braking

A braking force generated by braking is expressed as a product of a tireload and a friction coefficient. A vehicle reduces speed at a rate proportional to a sum of braking forces. An inertia force, which is the same in magnitude as the sum of the braking forces, but in an opposite direction, i.e., in the driving direction, acts on the center of gravity of the vehicle. Therefore, a torque is generated, which tends to plunge the vehicle forward, resulting in an increase of ΔW_b in tire load for front wheels and a decrease of ΔW_b in tire load for rear wheels.

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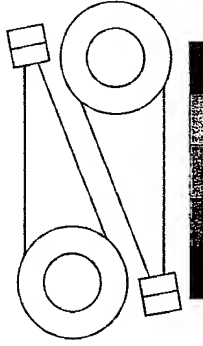
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SERIES

自動車用ABSの研究

Study on vehicle ABS

自動車用ABSの研究

Anti-lock Braking System

日本エービーエス株式会社 編
Edited by Japan ABS co., Ltd.



日本エービーエス株式会社 編

Publisher

San kaido

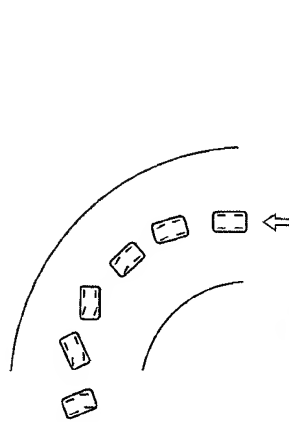


図 2-5 後輪だけがロックした場合 only rear wheels are locked up

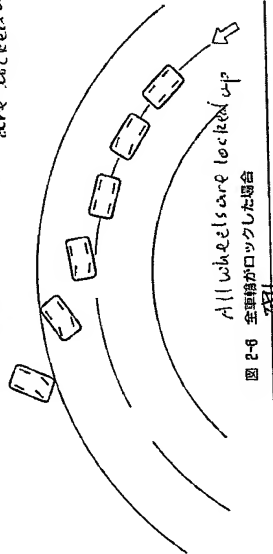


図 2-6 全車輪がロックした場合

れ、図 2-6 に示すように車両は上述の 2 つの現象を合わせた運動をする。すなわち、運転者のハンドルの操作とはまったく無関係に不規則な曲線を描きながら、運転方向に滑っていく。

以上述べたように、適当な強さでブレーキをかければ効果的に車両を停止させることができるが、ブレーキをかけ過ぎて車輪をロックさせると、それは種々の危険性を伴った車両の運動を生じさせる最大の原因となる。し

2.1 ブレーキ時の車両の運動 29

たがって、凍結路、雪道、砂利道、悪路、水に濡れた道路、乾いた道路、直進路、カーブなどの道路条件や、車両の速度、ハンドルの操作など道路条件や走行条件に応じて、常に車輪をロックさせないように注意してブレーキを操作しなければならない。

2.1.2 荷重の移動

車両の荷重は各々の車輪によって支えられている。そのためにタイヤと路面との接触面には図 2-7 に示すようなタイヤ荷重と呼ばれる垂直方向の力が作用している。そして、このタイヤ荷重は、ブレーキ時の制動力やコーナリング時の遠心力によって車両の重心に作用する慣性力（質量×加速度）のために、次のように変化する。

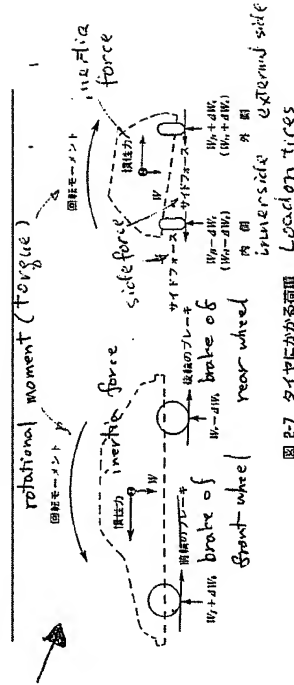


図 2-7 タイヤにかかる荷重 Load on tires

(1) 制動力による変化

ブレーキ時に発生する制動力は、タイヤ荷重と制動摩擦係数の積で表される。そして車両は制動力の総和に比例して減速するが、この力と同じ大きさで方向が逆、つまり進行方向を向いた慣性力が車両の重心に作用する。そのため、車両が前のめりになるような回転モーメントが生じ、前輪ではタイヤ荷重が ΔW_f だけ増加し、後輪では ΔW_r だけ減少する。制動摩擦係

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(Takaaki UNO)

Therefore, load on front wheels increases from 700 kg to 780 kg, while load on rear wheels decreases from 700 kg to 620 kg. As a result, according to load dependency of the cornering force, the cornering force of the front wheels increases, while the cornering force of the rear wheels decreases. This gives rise to a yaw moment as shown in Fig. 3-31(2), which causes the vehicle to spin. How should such a situation be handled?

There is only one thing a driver can do: brake and, at the same time, quickly turn the steering wheel back, so as to make the cornering force of the front wheels the same as the rear wheels, thereby avoiding a spin for the moment (Fig. 3-31(3)). However, there are not so many people capable of doing such steering at once. Mostly, a driver simply clings to the steering wheel and trusts to luck. Therefore, it is necessary to make improvement on the vehicle side.

b) Stability improvement using a suspension property

As an improvement using a suspension property, a general measure is a "toe-control" method. Specifically, the yaw moment shown in Fig. 3-31(2) can be reduced by making front wheels toe-out and rear wheels toe-in (Fig. 3-31(4)).

As a recent general trend, the toe-in property of the rear wheels arises in response to a longitudinal force applied to the suspension when braking, i.e., a so-called "longitudinal force compliance steer." On the other hand, the toe-out property of the front wheels is realized by combining the "longitudinal force compliance steer" and a "roll steer" that utilizes a dive (a plunge-forward posture of the vehicle) caused by braking, i.e., a "bound stroke."

However, in order to ensure braking stability, properly maintaining such suspension property alone is insufficient. As another important element, it is necessary to properly maintain braking force distribution between front and rear wheels. This subject will be introduced in section 1 of chapter 6. As a measure of further improving braking stability, there is a case where an LSD (Limited Slip Differential) property is used. This subject will be discussed in section 3 of chapter 6.

3-5 Vehicle posture control

(1) Vehicle posture control

Tilting backward at a sudden acceleration, tilting forward at braking, and making a large roll during a cornering are general images of dynamic posture changes of a vehicle. These posture changes of a vehicle appear to be natural, considering a longitudinal load shift due to inertia force caused by starting or braking, and lateral load shift due to a centrifugal force.

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Born in Kyoto in 1955. Completed master's program in engineering in the graduate school of the University of Tokyo. Joined Nissan Motor Co., Ltd. in 1981; in charge of Fairlady Z and Skyline suspension design and HICAS design. From 1992, in charge of vehicle chassis planning and suspension design. Currently, conducting FR vehicle chassis planning and suspension design, as a Chief for the First Chassis Design Section in the First Vehicle Design Department of the First Product Development Division. Main awards include Award of Society of Automotive Engineers of Japan for HICAS development and SAE Arch T. Colwell Merit Award of America for multi-link suspension development.

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performance of vehicular movement
and
mechanism of chassis
車両運動性能と
シャシーメカニズム

Uno Takaaki
宇野 高明

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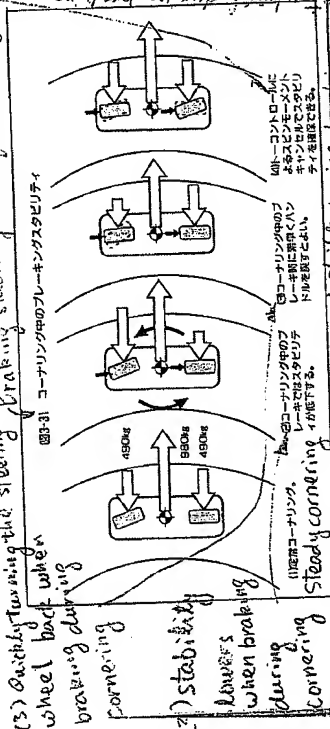
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Fig. 3-1- can be maintained by spin moment cancellation due to toe-control

(4) Stability λ non

(4) Stability \rightarrow stability during cornering

[illegible]

したがって前輪荷重は700kgから780kgへ増加し、また後輪荷重は700kgから620kgへ減少する。その結果コーナリングフォアースの荷重依存特性は、これは図3-31(2)のようフォアースを増大し、後輪のコーナリングフォアースは減少する。このような状況に陥った場合はどうすればよいか。

ドライバにできることはひとつ。ブレーキنگと同時にハンドルを瞬時に切り戻し、ドライバに同じにすれば、ひとはずはピンから逃れられる。前輪のコーナリングフォアースを後輪と同じにすれば、ひとはずはピンから逃れられる(図3-31(3))。しかし、とっさにこのようなハンドル操作ができる人はそう多くはない。たいていはハンドルがなくなつて道を天に任す状況となる。したがって、車側で前輪の傾を戻す必要がある。

4 Δw₁ + 4 Δw₂ + 2 Δw₃ + Δw₄ + Δw₅ + Δw₆ + Δw₇ + Δw₈ + Δw₉ + Δw₁₀ + Δw₁₁ + Δw₁₂ + Δw₁₃ + Δw₁₄ + Δw₁₅ + Δw₁₆ + Δw₁₇ + Δw₁₈ + Δw₁₉ + Δw₂₀ + Δw₂₁ + Δw₂₂ + Δw₂₃ + Δw₂₄ + Δw₂₅ + Δw₂₆ + Δw₂₇ + Δw₂₈ + Δw₂₉ + Δw₃₀ + Δw₃₁ + Δw₃₂ + Δw₃₃ + Δw₃₄ + Δw₃₅ + Δw₃₆ + Δw₃₇ + Δw₃₈ + Δw₃₉ + Δw₄₀ + Δw₄₁ + Δw₄₂ + Δw₄₃ + Δw₄₄ + Δw₄₅ + Δw₄₆ + Δw₄₇ + Δw₄₈ + Δw₄₉ + Δw₅₀ + Δw₅₁ + Δw₅₂ + Δw₅₃ + Δw₅₄ + Δw₅₅ + Δw₅₆ + Δw₅₇ + Δw₅₈ + Δw₅₉ + Δw₆₀ + Δw₆₁ + Δw₆₂ + Δw₆₃ + Δw₆₄ + Δw₆₅ + Δw₆₆ + Δw₆₇ + Δw₆₈ + Δw₆₉ + Δw₇₀ + Δw₇₁ + Δw₇₂ + Δw₇₃ + Δw₇₄ + Δw₇₅ + Δw₇₆ + Δw₇₇ + Δw₇₈ + Δw₇₉ + Δw₈₀ + Δw₈₁ + Δw₈₂ + Δw₈₃ + Δw₈₄ + Δw₈₅ + Δw₈₆ + Δw₈₇ + Δw₈₈ + Δw₈₉ + Δw₉₀ + Δw₉₁ + Δw₉₂ + Δw₉₃ + Δw₉₄ + Δw₉₅ + Δw₉₆ + Δw₉₇ + Δw₉₈ + Δw₉₉ + Δw₁₀₀ + Δw₁₀₁ + Δw₁₀₂ + Δw₁₀₃ + Δw₁₀₄ + Δw₁₀₅ + Δw₁₀₆ + Δw₁₀₇ + Δw₁₀₈ + Δw₁₀₉ + Δw₁₁₀ + Δw₁₁₁ + Δw₁₁₂ + Δw₁₁₃ + Δw₁₁₄ + Δw₁₁₅ + Δw₁₁₆ + Δw₁₁₇ + Δw₁₁₈ + Δw₁₁₉ + Δw₁₂₀ + Δw₁₂₁ + Δw₁₂₂ + Δw₁₂₃ + Δw₁₂₄ + Δw₁₂₅ + Δw₁₂₆ + Δw₁₂₇ + Δw₁₂₈ + Δw₁₂₉ + Δw₁₃₀ + Δw₁₃₁ + Δw₁₃₂ + Δw₁₃₃ + Δw₁₃₄ + Δw₁₃₅ + Δw₁₃₆ + Δw₁₃₇ + Δw₁₃₈ + Δw₁₃₉ + Δw₁₄₀ + Δw₁₄₁ + Δw₁₄₂ + Δw₁₄₃ + Δw₁₄₄ + Δw₁₄₅ + Δw₁₄₆ + Δw₁₄₇ + Δw₁₄₈ + Δw₁₄₉ + Δw₁₅₀ + Δw₁₅₁ + Δw₁₅₂ + Δw₁₅₃ + Δw₁₅₄ + Δw₁₅₅ + Δw₁₅₆ + Δw₁₅₇ + Δw₁₅₈ + Δw₁₅₉ + Δw₁₆₀ + Δw₁₆₁ + Δw₁₆₂ + Δw₁₆₃ + Δw₁₆₄ + Δw₁₆₅ + Δw₁₆₆ + Δw₁₆₇ + Δw₁₆₈ + Δw₁₆₉ + Δw₁₇₀ + Δw₁₇₁ + Δw₁₇₂ + Δw₁₇₃ + Δw₁₇₄ + Δw₁₇₅ + Δw₁₇₆ + Δw₁₇₇ + Δw₁₇₈ + Δw₁₇₉ + Δw₁₈₀ + Δw₁₈₁ + Δw₁₈₂ + Δw₁₈₃ + Δw₁₈₄ + Δw₁₈₅ + Δw₁₈₆ + Δw₁₈₇ + Δw₁₈₈ + Δw₁₈₉ + Δw₁₉₀ + Δw₁₉₁ + Δw₁₉₂ + Δw₁₉₃ + Δw₁₉₄ + Δw₁₉₅ + Δw₁₉₆ + Δw₁₉₇ + Δw₁₉₈ + Δw₁₉₉ + Δw₂₀₀ + Δw₂₀₁ + Δw₂₀₂ + Δw₂₀₃ + Δw₂₀₄ + Δw₂₀₅ + Δw₂₀₆ + Δw₂₀₇ + Δw₂₀₈ + Δw₂₀₉ + Δw₂₁₀ + Δw₂₁₁ + Δw₂₁₂ + Δw₂₁₃ + Δw₂₁₄ + Δw₂₁₅ + Δw₂₁₆ + Δw₂₁₇ + Δw₂₁₈ + Δw₂₁₉ + Δw₂₂₀ + Δw₂₂₁ + Δw₂₂₂ + Δw₂₂₃ + Δw₂₂₄ + Δw₂₂₅ + Δw₂₂₆ + Δw₂₂₇ + Δw₂₂₈ + Δw₂₂₉ + Δw₂₃₀ + Δw₂₃₁ + Δw₂₃₂ + Δw₂₃₃ + Δw₂₃₄ + Δw₂₃₅ + Δw₂₃₆ + Δw₂₃₇ + Δw₂₃₈ + Δw₂₃₉ + Δw₂₄₀ + Δw₂₄₁ + Δw₂₄₂ + Δw₂₄₃ + Δw₂₄₄ + Δw₂₄₅ + Δw₂₄₆ + Δw₂₄₇ + Δw₂₄₈ + Δw₂₄₉ + Δw₂₅₀ + Δw₂₅₁ + Δw₂₅₂ + Δw₂₅₃ + Δw₂₅₄ + Δw₂₅₅ + Δw₂₅₆ + Δw₂₅₇ + Δw₂₅₈ + Δw₂₅₉ + Δw₂₆₀ + Δw₂₆₁ + Δw₂₆₂ + Δw₂₆₃ + Δw₂₆₄ + Δw₂₆₅ + Δw₂₆₆ + Δw₂₆₇ + Δw₂₆₈ + Δw₂₆₉ + Δw₂₇₀ + Δw₂₇₁ + Δw₂₇₂ + Δw₂₇₃ + Δw₂₇₄ + Δw₂₇₅ + Δw₂₇₆ + Δw₂₇₇ + Δw₂₇₈ + Δw₂₇₉ + Δw₂₈₀ + Δw₂₈₁ + Δw₂₈₂ + Δw₂₈₃ + Δw₂₈₄ + Δw₂₈₅ + Δw₂₈₆ + Δw₂₈₇ + Δw₂₈₈ + Δw₂₈₉ + Δw₂₉₀ + Δw₂₉₁ + Δw₂₉₂ + Δw₂₉₃ + Δw₂₉₄ + Δw₂₉₅ + Δw₂₉₆ + Δw₂₉₇ + Δw₂₉₈ + Δw₂₉₉ + Δw₃₀₀ + Δw₃₀₁ + Δw₃₀₂ + Δw₃₀₃ + Δw₃₀₄ + Δw₃₀₅ + Δw₃₀₆ + Δw₃₀₇ + Δw₃₀₈ + Δw₃₀₉ + Δw₃₁₀ + Δw₃₁₁ + Δw₃₁₂ + Δw₃₁₃ + Δw₃₁₄ + Δw₃₁₅ + Δw₃₁₆ + Δw₃₁₇ + Δw₃₁₈ + Δw₃₁₉ + Δw₃₂₀ + Δw₃₂₁ + Δw₃₂₂ + Δw₃₂₃ + Δw₃₂₄ + Δw₃₂₅ + Δw₃₂₆ + Δw₃₂₇ + Δw₃₂₈ + Δw₃₂₉ + Δw₃₃₀ + Δw₃₃₁ + Δw₃₃₂ + Δw₃₃₃ + Δw₃₃₄ + Δw₃₃₅ + Δw₃₃₆ + Δw₃₃₇ + Δw₃₃₈ + Δw₃₃₉ + Δw₃₄₀ + Δw₃₄₁ + Δw₃₄₂ + Δw₃₄₃ + Δw₃₄₄ + Δw₃₄₅ + Δw₃₄₆ + Δw₃₄₇ + Δw₃₄₈ + Δw₃₄₉ + Δw_{350</}

101

front and rear wheels during braking. (a steady cornering braking)

Stairs
Rear wheel
Front
Rear wheel
Front
Rear wheel

品は、
ある

THE

である。具体的には図3-31(2)の四項モデルに準じ、前掲はトーニアウト、後掲はトーニングに準じ、後掲のトーニング特性はプレイングに準じ、発生させるのが従前の一般的傾向である。いである。一方、前掲のトーニアウト特性について、プレイング時に発生するタイプ(正面姿勢でワークを利用した)「ロールスミア」を組み合わせた「ロールスミア」の特性の正逆化については不十分で、もうひとつの重負配分の適正化が必要となる。これについてはプレイング時のスタビリティを高める方策としては、6章を引用する場合もある。これについては、6章

勢いよく発達するときは尻下がりで、急ブレーキの時には大きなロールというのが一般的にイメージされる。このころに車の姿勢の変化は、発進・制動時の慣性によるものである。車の性能のことを考えれば至極当然のようであるがしかし、これらはサスペンションジョイントオメガトリックものである。他の性能のことを考えれば至極当然のようであるが

During acceleration
図-33 加速、減速時のブレーキ

(1) 加速時のため、発進ブレーキ下は、加速

(2)

frontward shifting at brake

if starting are general conc

メントを減らせよ!から、プレーキング
なればよい(図3-31(4))。

サスベンションに加わる前後力に応じて
やめる。前後力コンプライアンススステア
は、「前後力コンプライアンススステア
の前後下がり」、すなわちバウダストロ
実装している。

発生するにはこのようなサスベンション特
要な要素として、前後と後端のプレーキ
6章1節で紹介しよう。また、さらにア
ド、LSD(リミテッドスリップデフ)特
3節でみることにしよう。

氏の名前は前のめり。また、コーナリングされる車の軌跡が鋭化してある。力による前後荷重移動や、遠心力によるはる。

変位
 運動の制動係数
 and of acceleration
 and velocity
 suspension on
 depending on
 乗客の一回のイグニッション
 乗客の乗上がり、乗下り、乗車位置の移動
 ing and down ward tilting
 are also possible
 backward tilting at bro
 suspension geomet

ception of posture changing

宇野高明(うの.たかあき)

1955年京都府生まれ。東京大学大学院工学系研究科修士課程修了。
1981年日産自動車株式会社に入社し、フェアレディZ、スカイラインのサスペンション設計、HICASの設計を担当。1992年より乗用車のシャシー計画とサスペンション設計を担当。現在、第一商品開発本部第一車両設計部第一シャシー設計課主担としてFR乗用車のシャシー計画、サスペンション設計になぞらわっている。主な受賞歴として、HICASの開発で日本自動車技術会賞、マルチリックサスペンションの開発でアメリカSAEアークコークウェルメリット賞などがある。

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